

DAFTAR PUSTAKA

- Bijanrostami, Khosro.. Design and Development of an Automated Guided Vehicle for Educational Purpose. Gazimagusa. 2011.
- Prabowo , & Mahardika. D. “Analisis Pengaruh Kecepatan dan Massa Beban pada Conveyor Belt terhadap Kualitas Pengemasan Dan Kebutuhan Daya dan Arus Listrik di Bagian Produksi PT Indopintan Sukses Mandiri Semarang”. Undergraduate Thesis. Semarang: Universitas Muhammadiyah Semarang 2018.
- Anandya, G. R. “Rancang Bangun Lengan Robot Penjepit Pcb 3 Dof Berbasis Arduino Untuk Proses Etching PCB Otomatis”. Surabaya: ITS. 2017.
- M. Khorasani.”Design and Kinematics Modeling of a Novel Haptic Device”. 5th RSI Int. Conf. Robot. Mechatronics, no. IcRoM, pp. 421–425. 2017.
- M. Mustafa, R. Misuari, and H. Daniyal.. Forward Kinematics of 3 Degree of Freedom Delta Robot. no. December, pp.3–6, 2007.
- J. Billingsley and J. Billingsley. “Inverse Kinematics. Essentials Dyn”. Vib., pp. 95–98. 2017.
- Setiawan, Iwan. Buku Ajar Sensor Dan Transduser. Yogyakarta. 2009.
- Jaya, Hendra. “Desain dan Implementasi Sistem Robotika Berbasis Mikrokontroler”. Makassar: Edukasi Mitra Grafika.2016.
- Immersa Lab. “Pengertian Proxy Sensor, jenis-jenis, dan prinsip kerja”. 2018.
- Rachman, T. (2013). Penggunaan metode work sampling untuk menghitung waktu baku dan kapasitas produksi karungan soap chip di PT. SA. Universitas Esa Unggul.

- S. Sudimanto and K. Kevin, "Perancangan Robot Pemindah Barang Berbasis Line Follower," *TESLA J. Tek. Elektro*, vol. 22, no. 1, p. 1, 2020, doi: 10.24912/tesla.v22i1.7807.
- D. P. Angin et al., "Perancangan Robot Lengan Pemindah Barang Berdasarkan Jarak," *Semin. Nas. Inov. dan Ilmu Komput.*, no. April, pp. 84–87, 2018.
- G. Pegman, "The Strategic Research Agenda for Robotics in Europe," 2010.
- Y. Yamamoto, "Coordinated Control of A Mobile Manipulator," *Robotica*, vol. 16, no. March, pp. 607–613, 1994, [Online]. Available: http://repository.upenn.edu/cis_reports/240/.
- I. Farkhatdinov and J.-H. Ryu, *Switching of Control Signals in Teleoperation Systems: Formalization and Application*. 2008.
- R. Supriyanto, Hustinawati, R. Nugraini, A. Bima Kurniawan, Y. Permadi, and A. Sa'ad, *ROBOTIKA*, vol. 1. 2010.
- R. Syam and J. Hair, "Desain Kerjasama Mobile Manipulator Robot," *J. Otomasi Kontrol dan Instrumentasi*, vol. 8, no. 2, p. 125, 2016, doi: 10.5614/joki.2016.8.2.1.
- T. G. Sugar and V. Kumar, "Control of cooperating mobile manipulators," *IEEE Trans. Robot. Autom.*, vol. 18, no. 1, pp. 94–103, 2002, doi: 10.1109/70.988979.
- C. Perrier, P. Dauchez, and F. Pierrot, *A global approach for motion generation of non-holonomic mobile manipulators*, vol. 4. 1998.
- B. Bayle, J. Y. Fourquet, and M. Renaud, "Manipulability analysis for mobile manipulators," *Proc. - IEEE Int. Conf. Robot. Autom.*, vol. 2, pp. 1251–1256, 2001, doi: 10.1109/robot.2001.932782